A Program Transformation for Continuation Call-Based Tabled Execution

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Abstract. The advantages of tabled evaluation regarding program termination and reduction of complexity are well known—as are the significant implementation, portability, and maintenance efforts that some proposals (especially those based on suspension) require. This implementation effort is reduced by program transformation-based continuation call techniques, at some efficiency cost. However, the traditional formulation of this proposal by Ramesh and Cheng limits the interleaving of tabled and non-tabled predicates and thus cannot be used as-is for arbitrary programs. In this paper we present a complete translation for the continuation call technique which, using the runtime support needed for the traditional proposal, solves these problems and makes it possible to execute arbitrary tabled programs. We present performance results which show that CCall offers a useful tradeoff that can be competitive with state-of-the-art implementations.

Keywords: Tabled logic programming, Continuation-call tabling, Implementation, Performance, Program transformation.

1 Introduction

Tabling [18,19,4] is a strategy for executing logic programs which uses memoization of already processed calls and their answers to improve several of the limitations of SLD resolution. It brings termination for bounded term-size programs and improves efficiency in programs which perform repeated computations and has been successfully applied to deductive databases [14], program analysis [20,5], reasoning in the semantic Web [23], model checking [13], etc.

However, tabling also has certain drawbacks, including that predicates to be tabled have to be selected carefully³ in order not to incur in undesired slowdowns and, specially relevant to our discussion, that its efficient implementation is generally complex. In suspension-based tabling the computation state of suspended tabled subgoals has to be preserved to avoid backtracking over them. This is done either by freezing the stacks, as in XSB [17], by copying to another

³ XSB includes an auto_table declaration which triggers a conservative analysis to detect which predicates are to be tabled in order to ensure termination. However, more predicates than needed can be selected.
area, as in CAT [8], or by using an intermediate solution as in CHAT [9]. Linear tabling maintains instead a single execution tree without requiring suspension and resumption of sub-computations. The computation of the (local) fixpoint is performed by making subgoals “loop” in their alternatives until no more solutions are found. This may make some computations to be repeated. Examples of this method are the linear tabling of B-Prolog [22,21] and the DRA scheme [10]. Suspension-based mechanisms achieve very good performance but, in general, require deeper changes to the underlying implementation. Linear mechanisms, on the other hand, can usually be implemented on top of existing sequential engines without major modifications.

The Continuation Call (CCall) approach to tabling [15,16] tries to combine the best of both worlds: it is a reasonably efficient suspension-based mechanism which requires relatively simple additions to the Prolog implementation / compiler,\(^4\) thus making maintenance and porting much easier. In [6] we proposed a number of optimizations to the CCall approach and showed that with such optimizations performance could be competitive with traditional implementations. However, this was only partially satisfactory since the CCall tabling approach is restricted to programs with a certain interleaving of tabled and non-tabled predicate calls (see Figure 3 and Section 3.1), and thus cannot execute general tabled programs.

In this paper we present an extension of the CCall translation which, using the same runtime support of the traditional proposal, overcomes the problems pointed out above. In Section 5 we present a complexity comparison of the proposed approach with CHAT. Finally, we present performance results from our implementation. These results show that our approach offers a useful tradeoff which can be competitive with state of the art implementations, while keeping implementation efforts relatively low.

2 The Continuation Call Technique

We sketch now how tabled evaluation [4,17] works from a user point of view and we briefly describe the Continuation Call technique, on which we base our work.

2.1 Tabling Basics

We will use as example the program in Figure 1, whose purpose is to determine the reachability of nodes in a graph. If the graph contains cycles, there will be queries which will make the program loop forever under the standard SLD resolution strategy, regardless of the order of the clauses. Tabling changes the operational semantics for predicates marked with the :- table declaration, which forces the compiler and runtime system to distinguish the first occurrence of a tabled goal (the generator) and subsequent calls which are identical up to variable renaming (the consumers). The generator applies resolution using the\(^4\) As an example, no modification to the underlying engine is needed.
program clauses to derive answers for the goal. Consumers suspend the current execution path (using implementation-dependent means) and start execution on a different branch corresponding to another clause of the predicate within which the execution was suspended. When such an alternative branch finally succeeds, the answer generated for the initial query (the generator) is inserted in a table associated with that generator. This makes it possible to reactivate consumers and to continue execution at the point where they were stopped. Thus, consumers do not use SLD resolution, but obtain instead the answers from the table where they were previously inserted by the generator. Predicates not marked as tabled are executed according to SLD resolution, hopefully with minimal overhead due to the availability of tabling. This can be graphically seen as the ability to suspend execution in a part of the tree which cannot progress (because it enters a loop) and continue it somewhere else, where a solution for the looping goal can be produced.

2.2 CCall by Example

CCall implements tabling by a combination of program transformation and side effects in the form of insertions into and retrievals from a table which relates calls, answers, and the continuation code to be executed after consumers read answers from the table. We will now sketch how the mechanism works using the path/2 example (Figure 1). The original code is transformed into the program in Figure 2 which is the one actually executed.

Roughly speaking, the transformation for tabling is as follows: an auxiliary predicate (slg_path/2) for path/2 is introduced so that calls to path/2 made from regular (SLD) Prolog execution do not need to be aware of the fact that path/2 is being tabled. The primitive slg/1 will make sure that its argument is executed to completion and will return, on backtracking, all the solutions found for the tabled predicate. To this end, slg/1 checks if the call has already been executed. If so, all its answers are returned by backtracking. Otherwise, control is passed to a new predicate (slg_path/2 in this case). slg_path/2 receives in its first argument the original call to path/2 and in the second argument the identifier of its generator, which is used to relate operations on the table with this initial call. Each clause of slg_path/2 is derived from a clause of the original path/2 predicate by:

- Adding an answer/2 primitive at the end of each clause of the original tabled predicate. answer/2 is responsible for inserting answers in the table after checking for redundancy.
- Instrumenting calls to tabled predicates using the slgcall/1 primitive. If this tabled call is a consumer, path_cont/3, along with its arguments, is recorded as (one of) the continuation(s) of its generator. If the tabled call is a generator, it is associated with a new call identifier and execution follows using the slg_path/2 program clauses to derive new answers (as done

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5 The unique name has been created for simplicity by prepending slg_ to the predicate name—any safe means of constructing a unique predicate symbol can be used.
Fig. 1. A sample program.

\begin{verbatim}
:- table path/2.
path(X, Z):-
  edge(X, Y),
  path(Y, Z).

:- table path/2.
path(X, Y):- slg(path(X, Y)).
  slg_path(path(X, Y), ld):-
    edge(X, Y),
    slgcall (path_cont(ld, [X], path(Y, Z))).
  slg_path(path(X, Y), ld):-
    edge(X, Y),
    answer(ld, path(X, Y)).

path_cont(ld, [X], path(Y, Z)):-
  answer(ld, path(X, Z)).
\end{verbatim}

Fig. 2. The program in Figure 1 after being transformed for tabled execution.

by \texttt{slg/1}. Besides, \texttt{path\_cont/3} will be recorded as a continuation of the generator identified by \texttt{Id} if the tabled call cannot be completed (there were dependencies on previous generators). The \texttt{path\_cont/3} continuation will be called consuming found answers or erased upon completion of its generator. 

- Encoding the remaining of the clause body of \texttt{path/2} after the recursive call by using \texttt{path\_cont/3}. It is constructed similarly to \texttt{slg\_path/2}, i.e., applying the same transformation as for the initial clauses and calling \texttt{slgcall/1}.

The second argument of \texttt{path\_cont/3} is a list of bindings needed to recover the environment of the continuation call. Note that, in the program in Figure 1, an answer to a query such as \texttt{?- path(X, Y)} may need to bind variable \texttt{X}. This variable does not appear in the recursive call to \texttt{path/2}, and hence it does not appear in the \texttt{path/2} term passed on to \texttt{slgcall/1} either. In order for the body of \texttt{path\_cont/3} to insert in the table the answer corresponding to the initial query, variable \texttt{X} (and, in general, any other necessary variable) has to be passed down to \texttt{answer/2}. This is done with the list \texttt{[X]}, which is inserted in the table as well and completes the environment needed for the continuation \texttt{path\_cont/3} to resume the previously suspended call.

A safe approximation of the variables which should appear in this list is the set of variables which appear in the clause before the tabled goal and which are used in the continuation, including the \texttt{answer/2} primitive. Variables appearing in the tabled call itself do not need to be included, as they will be passed along anyway. This list of bindings corresponds to the frame of the parent call if the \texttt{answer/2} primitive is added to the end of the body being translated. More details about \texttt{CCall} approach and their primitives can be found at [15].

**Key Contribution of CCall:** a new predicate name is created for all points where suspension can happen. Suspension is performed by saving this predicate name, a list of bindings, and a generator identifier. Resumption is performed by constructing a Prolog goal with the information saved on suspension plus the answer which raised the resumption. It is clear that this is significantly simpler.
t(A):- slg(t(A)).

slg_t(t(A), ld):-
    p(B), A is B + 1,
    answer(ld, t(A)).

Fig. 3. A program for which the original CCall transformation fails.

Fig. 4. The program in Figure 3 after being transformed for tabled execution.

t(A):- slg(t(A)).

slg_t(t(A), ld):-
    p(B), A is B + 1,
    answer(ld, t(A)).

The execution of the program with the query t(A) is shown in Figure 5. The execution is correct until slg/1 is called again by p/1. At that point execution should suspend (and later resume), but slg/1 does not have any associated continuation, and it does not have any pointer to the code to be executed on resumption (partially in p/1 and partially in slg_t/2): B < 1, A is B + 1, answer(Id, t(A)) is lost on backtracking and it is not reachable when resuming. Consequently, the second answer to the query, t(1), is lost.

The call to t(B) made by p(B) could have been translated as if it were in the body of a tabled clause, but in that case the piece of code A is B + 1 in
the first clause of \( t/1 \) would be lost anyway. This is an example of why all the frames between a consumer and its nearest generator have to be saved when suspending, and it is not enough to save just the last one, as in the original \texttt{CCall} proposal [15], which does work, however, when all the calls to the tabled predicates appear in the body of the clause of a tabled predicate. In that case, it is enough to save the last frame with the associated continuation code. Note that all the suspension-based tabling approaches preserve the frames / environments from the consumer until the corresponding generator.

To solve this problem, we have extended the translation to take into account a new kind of predicates, named \textit{bridges}. A bridge predicate is a non-tabled Prolog predicate whose clauses generate frames which have to be saved in the continuation of a consumer. In the example of Figure 3, \( p/1 \) is a bridge predicate.

### 3.2 Marking Predicates as Bridges

Bridge predicates are all the non-tabled predicates which can appear in the execution tree of a query between a generator and each of its consumers, i.e., the predicates whose environments are in the local stack between the environment of the generator and the environment of each of its consumers. Note that tabled predicates do not need to be included as bridge predicates as their environment will be already saved by the translation. Additionally, only recursive calls which can lead to infinite loops under SLD resolution have to actually be taken into account, because these are the only ones which can suspend and later be resumed. Programs for which tabling merely speeds up already terminating computations are not subject to the problem outlined above, and therefore do not benefit from the improved translation shown herein.

Thus, in order to determine a minimal set of bridge predicates, \( B_{\text{min}} \), we need to determine before the minimum set of tabled predicates, \( T_{\text{min}} \), which ensures
Make a graph $G$ with an edge $(p1/n1, p2/n2) \Leftrightarrow p2/n2$ is called from $p1/n1$

Bridges $= \emptyset$

FOR each predicate $T$ in TABLED PREDICATES

Forward $= \text{All predicates reached from } T \text{ in } G$

Backward $= \text{All predicates from which } T \text{ is reached in } G$

Bridges $= \text{Bridges} \cup (\text{Forward} \cap \text{Backward})$

Bridges $= \text{Bridges} - \text{TABLED PREDICATES}$

Fig. 6. Safe approximation to look for bridge predicates.

termination. When $T_{\text{min}}$ is found, $B_{\text{min}}$ is the set of non-tabled predicates which are “in the middle” of two calls to predicates belonging to $T_{\text{min}}$. Since looking for $T_{\text{min}}$ is undecidable (because it implies detecting infinite failures), looking for $B_{\text{min}}$ is also undecidable and a safe approximation, which may mark as bridge some predicates which do not need to be, is needed.

As we will see in Section 4, the only disadvantage of such an over-approximation is that some code will be duplicated (to accept a new argument for the case where a bridge predicate is called from a tabled execution), and that bridge predicates, having an extra argument, can be called when this is not needed. The algorithm we have implemented (Figure 6) only looks for tabled predicates which can recursively call themselves. For the examples used for performance evaluation in Section 6, using the safe approximation algorithm produces an average slowdown of only 3% with respect to a perfect characterization of bridge predicates.

4 A General Translation for Tabled Programs

In this section we present program transformation rules which take into account bridge predicates. This transformation assumes that the safe approximation algorithm for bridge predicates has already been run, and all the bridge predicates have been marked by adding a :- bridge P/N declaration in the program.

As seen in Section 2.2, a continuation is the way to save an environment, because the predicate name is the same as the PC counter of the environment and the list of bindings is the same as the variables that a environment saves. Consequently, the goal of the new translation is to associate a continuation with each of the bridge predicates to save their associated environment. These continuations receive a new argument (the continuation to be executed) which is used to push a pointer (i.e., the name of a predicate) to the code to continue with, in a way similar to environments in local stacks.

4.1 Translation Rules

The rules for the original translation have three different goals: to maintain the interface with the rest of the code, to manage tabled calls which appear in the body of the clauses of a tabled predicate, and to insert answers at the end of
the evaluation of each clause. The same points have to be addressed for bridge clauses, taking into account that a tabled or bridge call has to be translated if it appears in the body of a tabled predicate or a bridge predicate.

The rules for the new translation, which uses the same primitives as the original CCall proposal, are shown in Figure 7, where for conciseness we have used a sugared Prolog-like language. For example, a functional syntax is implicitly assumed where needed, and infix 'o' is a general append function which joins either (linear) structures or, when applied to atoms, concatenates them. It may appear in an output head position with the expected semantics.
The trans/2 predicate receives a clause to be translated and returns the list of clauses resulting from the translation. Its first clause ensures that predicates which are non-tabled and non-bridge are not transformed. The second one is to generate the interface of table predicates with the rest of the code: if there is a tabled declaration, the interface is generated. The third clause translates clauses of tabled predicates, and the fourth one translates clauses of bridge predicates, where the original one is maintained in case it is called outside a tabled call (this is in order to preserve the interface with non-tabled code). They generate the new head of the clause, Head.tr, and the code which has to be appended at the end of the body, End, before calling transBody/6 with these arguments. End can be the answers/2 primitive for tabled clauses or call(Cont), which invokes the following pushed continuation, stored in the fourth argument.

transBody/6 generates, in its last argument, the translation of the body of a clause by taking care, in each iteration, of the code until the next tabled or bridge call, or until the end of the clause, and appending the translation of the rest of the clause to this partial translation. In other words, it calls updateBody/8 to translate tabled or bridge calls and continues translating the rest of the body.

The following/4 splits a clause body in three parts: a prefix, until the first time a tabled or bridge call appears, the tabled or bridge call itself, and a suffix from this call until the end of the clause. getLBinds/3 obtains the list of variables which have to be saved to recover the environment of the consumer, based on the ideas of Section 2.2.

The updateBody/8 predicate completes the body prefix until the next tabled or bridge call. Its first six arguments are inputs, the seventh one is the head of the continuation for the suffix of the body, and the last argument is the new translation for the prefix. The first clause takes care of the base case, when there are no calls to bridge or tabled predicates left, the second clause generates code for a call to a tabled predicate, and the last one does the same with a bridge predicate. That getNameCont/1 generates a unique name for the continuation.

We will now use the example in Figure 3, adding a :- bridge p/1 declaration, to exemplify how a translation would take place.

4.2 The Previous Example with the Correct Transformation

The translation of the first clause of t/1 is done by the third clause of trans/2, which makes the head of the translated clause to be slg.t(t(A), Id) and states that the final call of that clause has to be answer(Id, t(A)) —i.e., when the clause successfully finishes, it adds the answer to the table.

transBody/6 takes care then of the rest of the body, which identifies which environment variables (A, in this case) have to be saved and matches Pref, Pred, and Suff with the goals before the call to the bridge predicate (none —

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6 The predicates table/1 and bridge/1 are dynamically generated by the compiler from the corresponding declaration. They check if their argument is a clause of a tabled or bridge predicate, or if their argument is a functor corresponding to a tabled or bridge predicate, respectively.
t(A) := slg(t(A)).
slg_t(t(A), ld) :-
    p_bridge(p(B), ld, slg_t0(ld, [A], p(B), [])).
slg_t(t(0), ld) :- answer(ld, t(0)).
slg_t0(ld, [A], p(B), []) :-
    A is B + 1,
    answer(ld, t(A)).
p(B) := t(B), B < 1.
p_bridge(p(B), ld, Cont) :-
    slgcall(p_bridge0(ld, [], t(B), Cont)).
p_bridge0(ld, [], t(B), Cont) :-
    B < 1,
    call(Cont).

Fig. 8. The program in Figure 3 after being transformed for tabled execution.

and empty conjunction), the call to the bridge predicate (p(B)), and the goals after this call (A is B + 1). The third clause of updateBody/8 generates the body of Head.tr, to give the first clause of slg_t/2. A continuation is generated for the rest of the body; the code of the continuation is a predicate whose head is slg_t0/3 and its body is generated by the first clause of updateBody/8.

The translation of the second clause of t/1 is simpler, as it only has to add answer(ld, t(0)) at the end of the body of the new predicate.

The clause for p/1 is kept to maintain its interface when it is not called from inside a another tabled execution. The translation for the clause of p/1 is made by the fourth clause of trans/2 where Head.tr is unified with p_bridge(p(B), ld, Cont). End is unified with call(Cont) — a call to the continuation code to be resumed by the following pushed continuation. transBody/6 finds an empty list of environment variables and unifies Pref, Pred and Suff with [], t(B) and B < 1, respectively. The second clause of updateBody/8 generates the body for the new predicate p_bridge/3. A continuation is generated to execute the rest of the body, whose head is p_bridge0/3 and whose body is generated by the first clause of updateBody/8. As we can see, bridge predicates are pushing continuations which are sequentially called when consumers are resumed.

4.3 Execution of the Transformed Program

The execution tree of the transformed program is shown in Figure 9. It is similar to that in Figure 5, but a continuation slg_t0(id, [A], p(B), []) is passed to the transformed clause of p/1. This continuation contains the code to be executed after the execution of p(B) and the list [A] needed to recover its environment. Consequently, there are two continuations associated with the suspension: one continuation to execute the rest of the code of p(B) and another one to execute the rest of the code of t(A).

After the first answer is found, this double continuation is resumed. It is executed as a normal Prolog and the second answer, t(1), is found.
5 $\Theta$(CHAT) is not comparable with $\Theta$(CCall)

In this section we present a comparative analysis of the complexity of CCall and CHAT, which is an efficient implementation of tabling with a comparatively simple machinery. Since it is known that $\Theta$(CHAT) is $\Theta$(SLG-WAM) [7], the comparative analysis applies to the SLG-WAM as well.

The complexity analysis focuses on the operations of suspension and resumption. The environment of a consumer has to be protected when suspending to reinstall it when resuming. CCall achieves that by copying the continuation associated with the consumer in a special memory area to be protected on backtracking. In the original implementation [15] this continuation is copied from the heap to a separate table (when suspending) and back (when resuming). As proposed in [6], continuations can be saved in a special memory area with the same data format as the heap. This makes it possible to use WAM instructions and additional machinery on them and, when resuming, they can be used as normal Prolog data and code, without being recopied each time a consumer is resumed.

On the other hand, CHAT freezes the heap and the frame stack when resuming. The heap and frame stack are frozen by traversing the choice point stack. For all the choice points between the consumer choice point and its generator, the pointer to the end of the heap and frame stack are changed to the values of the consumer choice point values. By doing that, heap and frame stack are protected on backtracking. However, the consumer choice point has to be
copied to a special memory area as well as the segment trail (with its associated values) between the consumer and the generator, to reinstall the values of the bound variables at the time of suspension which backtracking will unbind. In consequence, when resuming the trail values have to be reinstalled as well as the consumer choice point.

Each consumer is suspended only once, and it can be resumed several times. The rest of the operations, i.e., checking if a tabled call is a generator or a consumer, are not analyzed, because they are common to both systems. In addition, we will ignore the cost of working at the Prolog level, since this is an orthogonal issue: CCall primitives could be compiled to WAM instructions and working at Prolog level does not increase the system complexity.

$\Theta$(CCall): when suspending, CCall has to copy all the environments until the last generator and the structures in the heap which hang from them. If we name $E$ the size of all the environments and $H$ the size of the structures in the heap, the time consumption when suspending is: $\Theta(E + H)$.

When resuming, CCall just has to perform pattern matching of the continuation against its clause. The time taken by the pattern matching depends on the size of the list of bindings, which is known to be $\Theta(E)$. Since each consumer can be resumed $N$ times, the time consumption of resuming consumers is $\Theta(N \times E)$.

$\Theta$(CHAT): when suspending, CHAT has to traverse the frame and choicepoint stacks, but with the improvements presented in [7], the time this takes can be neglected because a choice point is only traversed once for all the consumers. The trail and the last choice point have to be copied. If we call $T$ the size of the trail and $C$ the size of the choice point, which is bound by a constant for a given program, the time consumption when suspending is: $\Theta(T)$.

When resuming, CHAT has to reinstall the values of the frame and the choice point. Since each consumer can be resumed $N$ times, the time consumption of resuming is $\Theta(N \times T)$.

**Analyzing the worst cases of both systems:** we can conclude $E + H \geq T$, because each variable can only be once in the trail, and then CCall is worse than CHAT when suspending. On the other hand, in case that $E < T$, CCall is better than CHAT when resuming. Consequently, for a plausible general case, the more resumptions there are, the better CCall behaves in comparison with CHAT, and conversely. In any case, the worst and best cases for each implementation are different, which makes them difficult to compare. For example, if there is a very large structure pointed to from the environments, and none of its elements are pointed to from the trail, CCall is slower than CHAT, since it has to copy all the structure in a different memory area when suspending and CHAT does nothing both when suspending and when resuming.

On the other hand, if all the elements of the structure are pointed to from the trail, CCall has to copy all the structure on suspension in a different memory area
to protect it on backtracking, but it is ready to be resumed without any other
operation (just a unification with the pointer to the structure). CHAT has to
copy all the structure on suspension too, because all the structure is in the trail.
In addition, each time the consumer is resumed, all the elements of the structure
have to be reinstalled using the trail, and CHAT has to perform more operations
than CCall, and then, the more resumptions there are, the worse CHAT would
be in comparison with CCall. Anyway, as the trail is usually much smaller than
the heap, in general cases, CHAT will have an advantage over CCall.

6 Performance Evaluation

We have implemented the proposed technique as an extension of the Ciao sys-
tem [1]. Tabled evaluation is provided to the user as a loadable package that
implements the new directives and user-level predicates, performs the program
transformations, and links in the low-level support for tabling. We have imple­
mented CCall tabling with the efficiency improvements presented in [6] and the
new translation for general programs explained in this paper.

Table 1 aims at determining how the proposed implementation of tabling
compares with state-of-the-art systems —namely, the latest available versions
of XSB, YapTab, and B-Prolog, at the time of writing, using the typical bench-
marks which appear in other performance evaluations of tabling approaches.\footnote{This is in contrast to [6] where, due to the limitations of the CCall approach the benchmarks presented did not need the use of bridge predicates.}
In this table we provide, for several benchmarks, the raw time (in milliseconds)
taken to execute them using tabling. Measurements have been made with Ciao-
1.13, using the standard, unoptimized bytecode-based compilation, and with the
CCall extensions loaded, as well as in XSB 3.0.1, YapTab 5.1.1, and B-Prolog
7.0. Note that we did not compare with CHAT, which was available as a configu-
ration option in the XSB system and which was removed in recent XSB versions.
CHAT can be expected to be at least as fast (if not slightly faster) than XSB.

All the executions were performed using local scheduling and disabling garbage
collection; in the end this did not impact execution times very much. We used gcc
4.1.1 to compile all the systems, and we executed them on a machine with
Fedora Core Linux, kernel 2.6.9, and an Intel Xeon DESCHUTES processor.

The first benchmark is path, the same as Figure 1, which has been executed
with a chain-shaped graph. Since this is a tabling-intensive program with no con­
sumers in its execution, the difference with other systems is mainly due to having
large parts of the execution done at Prolog level. The following five benchmarks,
until atr2, are also tabling intensive. As their associated environments are very
small, CCall is far from its worst case (see Section 5), and the difference with
other systems is similar to that in path and for a similar reason. The worst case
in this set is tcn because there are two calls to slgcall/1 per generator, and
the overhead of working at the Prolog level is duplicated.

B-Prolog, which uses a linear tabling approach, suffers if costly predicates
have to be recomputed: this is what happens in benchmarks from pg until peep,
Table 1. Comparing Ciao+CCall with XSB, YapTab, and B-Prolog.

<table>
<thead>
<tr>
<th>Program</th>
<th>CCall</th>
<th>XSB</th>
<th>YapTab</th>
<th>BProlog</th>
<th># Bridges</th>
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<td>206.26</td>
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<td>117.70</td>
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<td>12.384</td>
<td>40.753</td>
<td>12</td>
</tr>
<tr>
<td>disj</td>
<td>18.095</td>
<td>15.762</td>
<td>9.2131</td>
<td>29.095</td>
<td>15</td>
</tr>
<tr>
<td>cs_o</td>
<td>34.176</td>
<td>27.644</td>
<td>18.169</td>
<td>85.719</td>
<td>14</td>
</tr>
<tr>
<td>cs_r</td>
<td>66.699</td>
<td>55.087</td>
<td>34.873</td>
<td>170.25</td>
<td>15</td>
</tr>
<tr>
<td>peep</td>
<td>68.757</td>
<td>58.161</td>
<td>37.124</td>
<td>150.14</td>
<td>10</td>
</tr>
</tbody>
</table>

where tabled and non-tabled execution is mixed. This is a well-known disadvantage of linear tabling techniques which does not affect suspension-based approaches. It has to be noted, however, that latest versions of B-Prolog implement an optimized variant of its original linear tabling mechanism [21] which tries to avoid reevaluation of looping subgoals.

In order to compare our implementation with XSB and YapTab, we must take into account that the speeds of XSB, and YapTab are different, at least in those cases where the program execution is large enough to be really significant (between 1.8 and 2 times slower in the case of XSB and 1.5 times faster in the case of YapTab).

In non-trivial benchmarks, from pg until peep, which at least in principle should reflect more accurately what one might expect in larger applications using tabling, execution times are in the end very competitive when comparing with XSB or YapTab. This is probably due to the fact that the raw speed of the basic engine in Ciao is higher than in XSB and closer to YapTab, rather than to factors related to tabling execution, but it also implies that the overhead of the approach to tabling used is reasonable after the proposed optimizations in [6]. In this context it should be noted that in these experiments we have used the baseline, bytecode-based compilation and abstract machine. Turning on global analysis and using optimizing compilers and abstract machines [11,3,12] can further improve the speed of the SLD part of the computation.

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8 Note that we are comparing the tabled-enabled version of Yap, which is somewhat slower than the regular Yap.
7 Conclusions

We have presented an extension of the continuation call technique which does not have the limitations of the original continuation call approach regarding the interleaving of tabled and non-tabled predicates. This approach has the advantage of being easier to implement and maintain than other techniques which require non-trivial modifications to low-level machinery. Although there is an overhead imposed by executing at Prolog level, we expect the speed of the source (Prolog) language to gradually improve by using global analysis, optimizing compilers, and better abstract machines. Accordingly, we expect the performance of CCall to improve in the future and thus gradually gain ground in the comparisons.

Although a non optimal tabled execution is obviously a disadvantage, it is worth noting that, since our implementation introduces only minimal changes in the WAM and none in the associated Prolog compiler, the speed at which regular Prolog is executed remains unchanged. In addition to this, the modular design of our approach gives better chances of making it easier to port to other systems. In our case, executables which do not need tabling have very little tabling-related code, as the data structures (for tries, etc.) are handled by dynamic libraries loaded on demand, and only stubs are needed in the regular engine. The program transformation is taken care of by a plugin for the Ciao compiler [2] (a “package,” in Ciao’s terms) which is loaded and active only at compile time, and which does not remain in the final executable.

References